



# Concurrent Models of Computation for Embedded Software

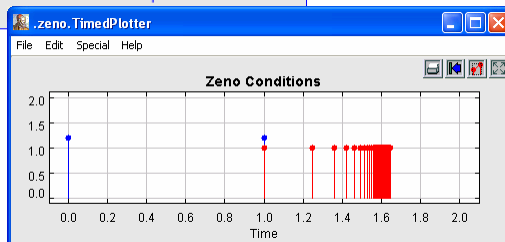
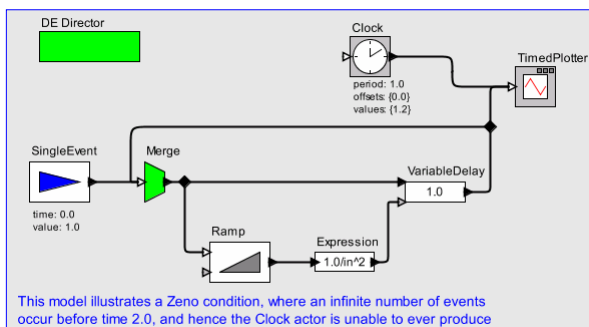
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EECS 290n – Advanced Topics in Systems Theory  
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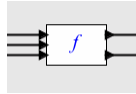
Lecture 13: Metric Space Semantics

## We Seek Semantics that Give Meaning to Feedback and Help Rule Out Zeno



## Mathematical Framework

Let the set of all signals be  $A = [T \rightarrow V]$  where  $T = R \times N$  is a totally ordered tag set and  $V$  is a set of values. Let an actor



be a function  $f: A^n \rightarrow A^m$ . What are the constraints on these functions such that:

1. Compositions of actors are determinate.
2. Feedback compositions have a meaning.
3. We can rule out Zeno behavior.

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## Metric

A **metric** on a set  $A$  is a function  $d: A \times A \rightarrow R$  where for all  $a, b, c \in A$

1.  $d(a, b) = d(b, a)$
2.  $d(a, b) = 0 \Leftrightarrow a = b$
3.  $d(a, b) + d(b, c) \geq d(a, c)$

Exercise: Show that these properties imply that for all  $a, b \in A$ ,  $d(a, b) \geq 0$

**Metric space:**  $(A, d)$

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## Variations on Metrics

*Ultrametric*: Replace property 3 with:

$$3. \max(d(a, b), d(b, c)) \geq d(a, c)$$

Exercise: Prove that an ultrametric is a metric.

*Partial Metric*: Replace properties 2 and 3 with:

$$2. d(a, a) \leq d(a, b)$$

$$3. d(a, b) + d(b, c) - d(b, b) \geq d(a, c)$$

In a partial metric,  $a$  is the “closest” object to itself.

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## The Cantor Metric

Given the tag set  $T = R \times N$  use only the time stamps. Let

$$d: [T \rightarrow V] \times [T \rightarrow V] \rightarrow R$$

such that for all  $s, s' \in [T \rightarrow V]$ ,

$$d(s, s') = 1/2^\tau$$

where  $\tau$  is the time stamp of the least tag  $t$  where  $s(t) \neq s'(t)$ . That is, either one is defined and the other not at  $t$  or both are defined but are not equal.

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## The Cantor Metric is an Ultrametric

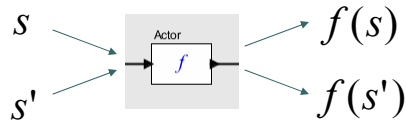
Need to show that for all signals  $a, b, c \in [T \rightarrow V]$ ,

1.  $d(a, b) = d(b, a)$
2.  $d(a, b) = 0 \Leftrightarrow a = b$
3.  $\max(d(a, b), d(b, c)) \geq d(a, c)$

(1) and (2) are obvious. To show (3), assume without loss of generality that  $d(a, b) \geq d(b, c)$ . This means that  $a$  and  $b$  differ earlier than  $b$  and  $c$ . Suppose that  $a$  and  $b$  differ first at time  $\tau$ . Since  $a$  and  $b$  differ earlier than  $b$  and  $c$ , then prior to  $\tau$ ,  $b$  and  $c$  are identical. Thus,  $a$  and  $c$  must be identical prior to  $\tau$  so  $d(a, c)$  must be smaller than or equal to  $d(a, b)$ . QED

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## Causality



**Causal:** For all signals  $s$  and  $s'$

$$d(f(s), f(s')) \leq d(s, s')$$

**Strictly causal:** For all signals  $s$  and  $s'$

$$s \neq s' \Rightarrow d(f(s), f(s')) < d(s, s')$$

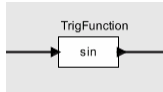
**Delta causal:** There exists a real number  $\delta < 1$  such that for all signals  $s$  and  $s'$

$$s \neq s' \Rightarrow d(f(s), f(s')) \leq \delta d(s, s')$$

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## Examples

Simple functional actor:



This actor is causal but not strictly causal or delta causal.

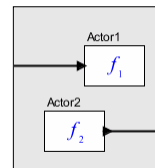
Time delay with non-zero delay:



This actor is delta causal.

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## Source and Sink Actors



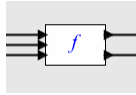
Consider Actor1. Its function is  $f_1: A^1 \rightarrow A^0$  where  $A^0$  is a *singleton set* (a set with one element). Such a function is always delta causal with  $\delta = 0$ .

Consider Actor2. Its function is  $f_2: A^0 \rightarrow A^1$ . Such a function is again always delta causal with  $\delta = 0$ . In fact, the function can only yield one possible output signal, since its domain has size 1.

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## Extending to Multiple Inputs/Outputs

Consider a function  $f: A^n \rightarrow A^m$ , where  $A = [T \rightarrow V]$



The input is a tuple of signals  $(a_1, a_2, \dots, a_n)$ .

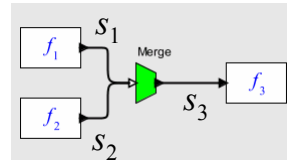
Extend the Cantor metric to handle tuples:

$$\begin{aligned} d((a_1, a_2, \dots, a_n), (b_1, b_2, \dots, b_n)) \\ = \min(d(a_1, b_1), \dots, d(a_n, b_n)) \end{aligned}$$

The resulting function is still an ultrametric.

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## Example: Merge Actor



Recall that for input

$$s_1 = \{\dots ((t, 0), v_1), ((t, 1), v_2), \dots\}$$

$$s_2 = \{\dots ((t, 0), q_1), ((t, 1), q_2), \dots\}$$

the output is:

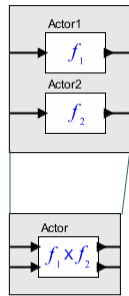
$$s_3 = \{\dots ((t, 0), v_1), ((t, 1), q_1), ((t, 2), v_2), ((t, 3), q_2), \dots\}$$

This actor is causal but not strictly causal, and the operations on indexes do not appear in the semantics.

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## Parallel Composition of Actors

If  $f_1$  and  $f_2$  are causal (strictly causal, delta causal), then so is  $f_1 \times f_2$ .

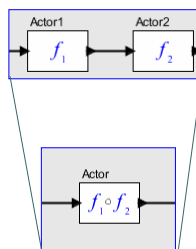


What if  $f_1$  is causal and  $f_2$  is delta causal?

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## Cascade Composition of Actors

If  $f_1$  and  $f_2$  are causal (strictly causal, delta causal), then so is  $f_1 \circ f_2$ .

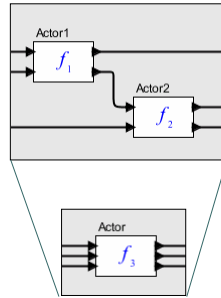


What if  $f_1$  is causal and  $f_2$  is delta causal?

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## More Interesting Composition

If  $f_1$  and  $f_2$  are causal (strictly causal, delta causal), then so is the following composition:



Question: What if  $f_1$  is causal and  $f_2$  is delta causal?

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## Technicality

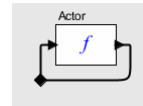
In the set  $S = [T \rightarrow V]$ , we could have a signal  $s$  that has, for example, an event at all integer time stamps (positive and negative), and we could compare it against a signal  $s'$  that has no events at all.

$$d(s, s') = \infty$$

This is problematic. We can avoid these problems by excluding from the set  $S$  all signals that have infinite distance from the empty signal. All such signals have an earliest event.

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## Feedback: Fixed Point Semantics

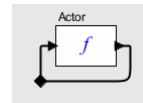


Since monotonicity on the prefix order is not very useful, we can't use fixed-point theorem 1.

Use instead fixed-point theorems on metric spaces.

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## Fixed Point Theorem 3



Let  $(S^n = [T \rightarrow V]^n, d)$  be a metric space and  $f: S^n \rightarrow S^n$  be a strictly causal function. Then  $f$  has at most one fixed point.

*Proof.* It is enough to show that

$$s \neq s' \Rightarrow f(s) \neq s \text{ or } f(s') \neq s'.$$

Suppose to the contrary that

$$s \neq s' \text{ and } f(s) = s \text{ and } f(s') = s'$$

But this is not possible because it would imply that

$$d(s, s') = d(f(s), f(s')) < d(s, s').$$

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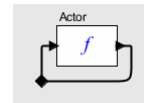
## Determinacy

Fixed-Point Theorem 3 takes care of determinacy. There can be no more than one behavior.

Can we find that behavior?

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## Fixed Point Theorem 4 (Banach Fixed Point Theorem)



Let  $(S^n = [T \rightarrow V]^n, d)$  be a *complete* metric space and  $f: S^n \rightarrow S^n$  be a delta causal function. Then  $f$  has a unique fixed point, and for any point  $s \in S^n$ , the following sequence converges to that fixed point:

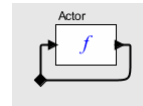
$$s_1 = s, s_2 = f(s_1), s_3 = f(s_2), \dots$$

**This means no Zeno!** Two issues:

- Any starting point?
- Complete metric space?

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## Construction of a Fixed Point: Example



Suppose  $f$  is a delay by one time unit, such that

$$s' = f(s)$$

where for each event  $e = (t, v) \in s$  where  $t = (\tau, n)$ , there is an event  $e' = (t', v) \in s'$  where  $t' = (\tau + 1, n)$ .

Suppose we start with a “lucky guess”  $s = \emptyset$ . This is the only fixed point, so we converge immediately.

Suppose we start with an “unlucky guess”  $s = \{((0,0), 0)\}$ . As we iterate  $f$ , the event gets further out in the future, and the signal “converges” to  $s = \emptyset$ .

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## Complete Metric Spaces

A *Cauchy sequence*  $\{s_1, s_2, \dots\}$  is an infinite sequence where

$$d(s_n, s_m) \rightarrow 0 \text{ as } n, m \rightarrow \infty$$

A *complete metric space*  $(X, d)$  is one where every Cauchy sequence has a limit in  $X$ .

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## Example 1

Consider a sequence  $\{s_1, s_2, \dots\}$  where

$$s_n = \{(n, 0), v\}$$

Is this sequence Cauchy?

Does the sequence converge? To what?

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## Example 1

Consider a sequence  $\{s_1, s_2, \dots\}$  where

$$s_n = \{(n, 0), v\}$$

Is this sequence Cauchy? **Yes**

$$d(s_n, s_m) = 1/2^{\min(m, n)} \rightarrow 0$$

Does the sequence converge? To what? **Yes. To  $\emptyset$**

$$\lim(s_n) = \emptyset$$

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## Example 2

Consider a sequence  $\{s_1, s_2, \dots\}$  where

$$s_n = \{(i, 0), v \mid i \in \{1, 2, \dots, n\}\}$$

Is this sequence Cauchy?

Does the sequence converge? To what?

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## Example 2

Consider a sequence  $\{s_1, s_2, \dots\}$  where

$$s_n = \{(i, 0), v \mid i \in \{1, 2, \dots, n\}\}$$

Is this sequence Cauchy? **Yes**

$$d(s_n, s_m) = 1/2^{\min(m, n) + 1} \rightarrow 0$$

Does the sequence converge? To what? **Yes. To**

$$\{(i, 0), v \mid i \in \{1, 2, \dots\}\}$$

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### Example 3

Consider a sequence  $\{s_1, s_2, \dots\}$  where

$$s_n = \{((\tau_i, 0), v) \mid i \in \{1, 2, \dots, n\}, \tau_i = 1 - 1/i\}$$

Is this sequence Cauchy?

Does the sequence converge? To what?

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### Example 3

Consider a sequence  $\{s_1, s_2, \dots\}$  where

$$s_n = \{((\tau_i, 0), v) \mid i \in \{1, 2, \dots, n\}, \tau_i = 1 - 1/i\}$$

Is this sequence Cauchy? **No**

$$d(s_n, s_m) > 1/2$$

Does the sequence converge? To what? **No. Exercise.**

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## Completeness of DE Signals

The set of  $n$ -tuples of discrete-event signals under the Cantor metric is a complete metric space.

*Proof (sketch):* We need to show that every Cauchy sequence converges. Given a Cauchy sequence  $\{s_1, s_2, \dots\}$ , for any tag  $t$  with time stamp  $\tau > 0$ , there is a subsequence  $\{s_n, s_{n+1}, \dots\}$ , for some  $n > 0$ , of signals that are identical up to and including tag  $t$ . Let  $s$  be the sequence obtained by letting its value at each tag  $t$  be that identical value (or absence, if all signals in the subsequence have no event at  $t$ ). This is clearly a signal (or tuple of signals). Then it is easy to show that the Cauchy sequence converges to  $s$ .

*Thanks to Adam Cataldo for this proof.*

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## Operational Semantics

1. Topologically sort actors according to paths that do not increment tags.
2. Start with a set of events on signals taken from the event queue that all have the same tag.
3. Iterate to find a fixed-point value for all signals at that tag (absent or having a value).
4. Continue with the next smallest tag in the event queue.

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## Conclusions and Open Issues

- Ignoring the index, strictly causal functions in a feedback loop have at most one fixed point, and hence are determinate.
- Delta causal functions in a feedback loop have exactly one fixed point, and that fixed point can be found by starting with any initial signal(s) and iterating to the fixed point. This guarantees no Zeno.
- Convergence in DE is achieved when time stamps approach infinity.
- Within a time stamp, use SR semantics and iterate to a fixed point.